

Unstructured grid modelling

Intercomparison between several
finite element and finite volume approaches
to model the North Sea tides

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Overall goals in ECOOP (Workpackage 7.2.1):

- ▶ To provide shallow water models working on unstructured grids and capable of being effectively coupled with larger-scale external models
- ▶ To provide adjoint models for optimising model parameters (friction, topography) and open boundary conditions
- ▶ Long-term goal: full 3D unstructured grid model for coastal applications

Work performed thus far in 7.2.1:

- ▶ Setup of several unstructured grid models (both FE and FV) for the North and Baltic Seas
- ▶ Exploring the influence of spatial discretization (FE, FV) on accuracy and computational efficiency

Unstructured grid models

finite volume (FV): easy to implement, less accurate in space

finite element (FE): implementation more elaborate, more expensive

FV:

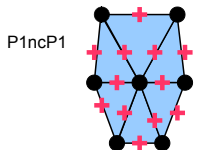
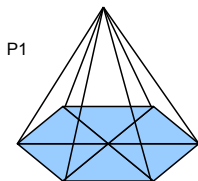
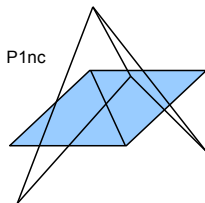
- ▶ Chen et al (FVCOM)
- ▶ Casulli&Walters (UnTRIM)

FE:

- ▶ wave continuity equation models (ADCIRC, QUODDY, MOG2D, T-UGO)
- ▶ other models (TELEMAC-2D, P1P1, NC)

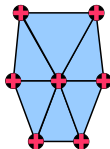
Question: Which approach provides better accuracy and is most efficient?

finite elements



+ velocity ● elevation

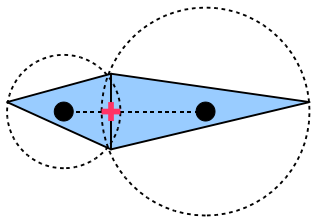
P1P1



- ▶ $P_1^{nc}P_1$ (NC): approx. 3x more edges than nodes
- ▶ P_1P_1 : pressure modes, stabilization

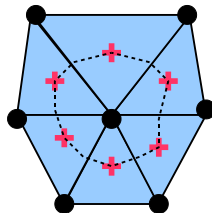
finite volumes

UnTRIM



- elevation at circumcenters
- ⊕ normal velocity at mid edges

FVCOM



- elevation at nodes
- ⊕ velocity at baricenters

Time stepping

- ▶ semi-implicit: bigger time steps, but matrix inversion (solver)
- ▶ explicit: small time steps for stability
- ▶ Runge-Kutta: more iterations per time step
- ▶ Adam-Bashforth: more storage

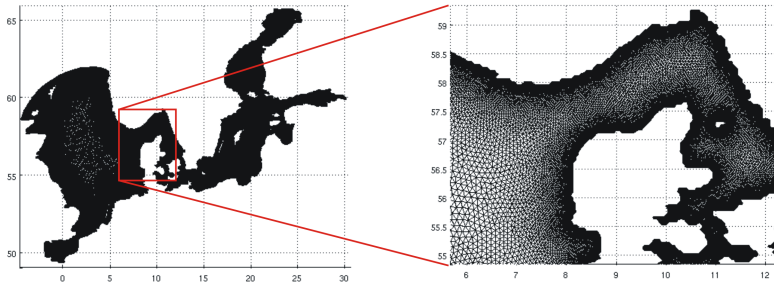
	Leap frog	Runge-Kutta	Adam-Bashforth	semi-implicit
P1P1				x
NC	x		(x)	x
FV		x	x	x

→ P1P1, NCLF, NCSI, FVAB, FVRK, FVSI

Model intercomparison in the North Sea

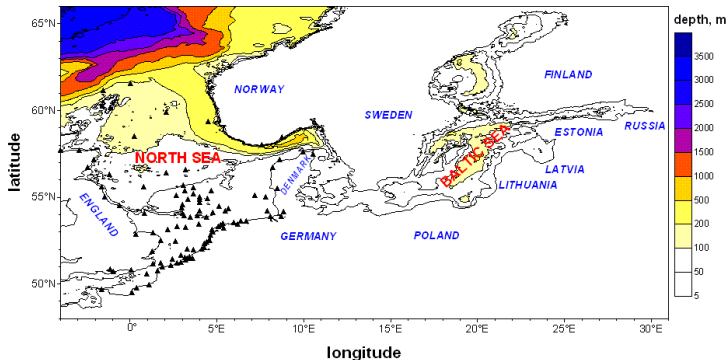
M2 tidal wave

- ▶ open boundary conditions: TPX06.2 (OTPS Egbert et al)
- ▶ closed boundary condition: free-slip
- ▶ bathymetry: GEBCO 1min

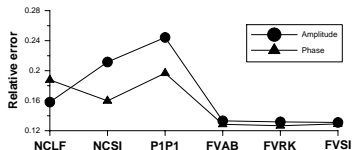
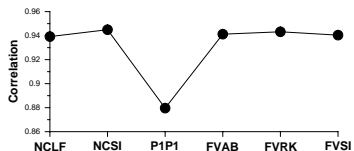
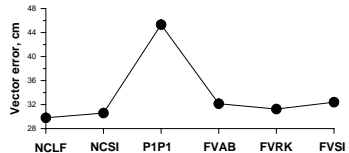
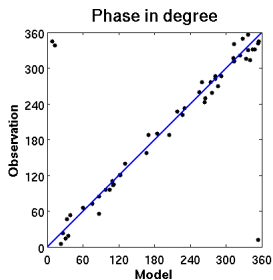
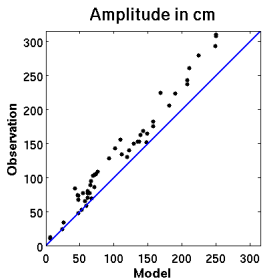


Limitations of North Sea intercomparison

- ▶ no wetting and drying (minimal depth of 5m)
- ▶ constant bottom friction
- ▶ bathymetry not tuned

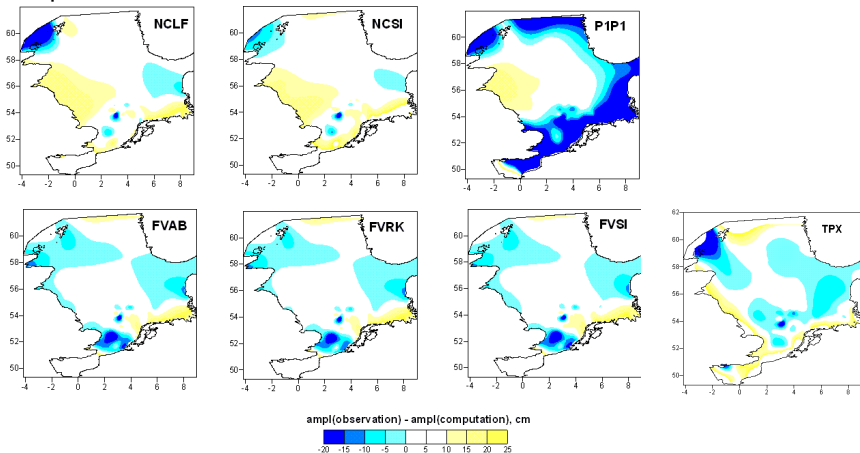


Error statistics

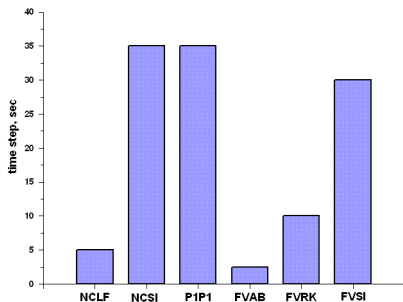
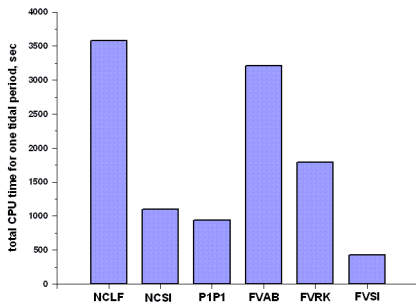


Error - spatial distribution

Amplitude



Computational cost



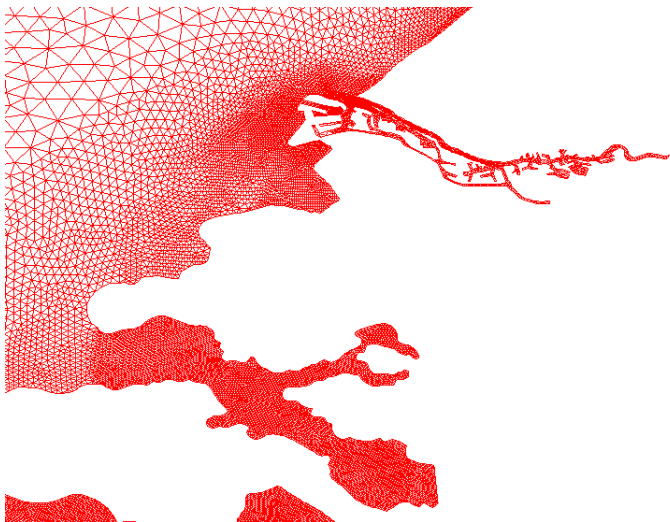
- ▶ IBM p655 cluster (5 nodes with 8 CPUs each)
- ▶ use of 1 CPU of a compute node (Power4+ system (1.7GHz) with 16 GByte Ram)
- ▶ size of the mesh
 - ▶ Number of nodes = 121699
 - ▶ Number of edges = 355589
 - ▶ Number of volumes = 233872

Ongoing work

Olga Kleptsova, TU Delft



Ongoing work



Conclusions

- ▶ all models compare reasonably well with observational data and produce close results
- ▶ semi-implicit codes are faster with same accuracy

Outlook

- ▶ adjoint model via automatic differentiation
- ▶ sensitivity of bottom topography and bottom friction
- ▶ optimization of parameters, initial and boundary condition
- ▶ wetting & drying (done for NC, under testing)
- ▶ astronomical tides (small changes in Baltic Sea)