

# Using automatic differentiation to optimize parameters of shallow water models in tidal applications

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# Outline

Goal: Unstructured tidal model with inverse estimation of parameters; adjoint model generation via automatic differentiation

Model status

Adjoint models and automatic differentiation

Results

Conclusions/Outlook

## Status of regional 2D tidal models

- ▶ Shallow water equations
- ▶ Triangular, unstructured meshes
- ▶ FV or FE with  $P_1^{NC}$   $P_1$  or  $P_1$   $P_1$  discretization
- ▶ Different time-stepping schemes
- ▶ Inclusion of tidal potential
- ▶ Wetting & drying
- ▶ Clamped or Flather open boundary condition

Tuning of parameters:

- ▶ Bottom friction coefficient ( $rH^{-1}|\mathbf{u}|\mathbf{u}$ )
- ▶ Depth
- ▶ Open boundary values

Adjusting parameters manually is time consuming as the number of unknowns is large.

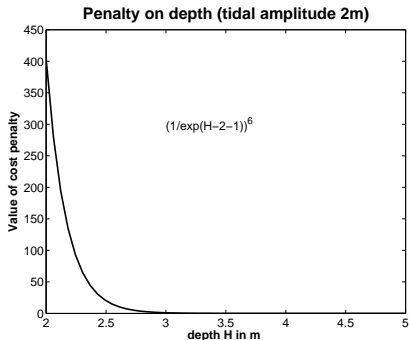
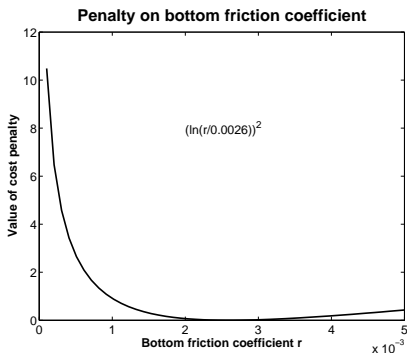
→ Inverse methods reconstruct from the misfit between model results and observations the correct parameters.

## Adjoint model

We minimize a cost function, which is calculated after each tidal cycle:

$$\begin{aligned}
 J = & \sum_{m=1}^M \left[ \left( B_m^{obs} - B_m^{mod} \right)^2 + \left( D_m^{obs} - D_m^{mod} \right)^2 \right] s_p \\
 & + \sum_{n=1}^N \left[ \left( \ln \left( \frac{r_n}{2.6 \cdot 10^{-3}} \right) \right)^2 s_c \right. \\
 & \left. + \left( \frac{1}{\exp(H_n - A_n^{mod} - 1)} \right)^6 s_h \right]
 \end{aligned}$$

$B$  resp  $D$  are the real resp imaginary part of the oscillations.  $A$  is the amplitude.  $r$  is the bottom friction coefficient.  $H$  is the depth.  $s_p$ ,  $s_c$  and  $s_h$  are scaling coefficients.  $M$  is the number of measurement points.  $N$  is the number of nodes.



... are a kind of regularization. It restricts the bottom friction parameter close to some initial guess and the bottom topography to stay in a range such that the depth is always positive.

## Automatic differentiation ...

... is a technology for automatically adding statements for the computation of derivatives to computer programs.

[www.autodiff.org](http://www.autodiff.org)

Advantages:

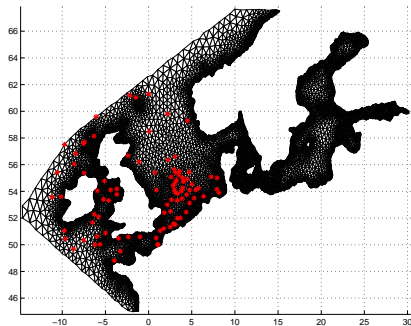
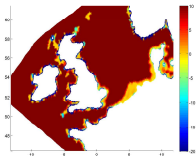
- ▶ Derivatives are accurate (contrary to FD methods)
- ▶ Adjoint model of the discretized equations
- ▶ Automatically generated adjoint models are easier to maintain
- ▶ Computation of Hessian for optimization algorithms is also possible
- ▶ Free software exists (TAMC, Tapenade, OpenAD,...)

# Test setup

The adjoint model is generated of the explicit non-conforming FE code using TAMC.

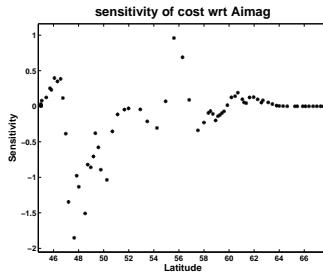
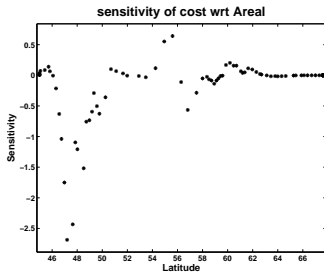
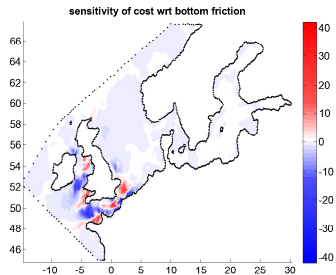
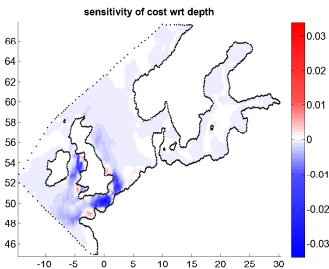
(clamped boundary condition, no wetting and drying, minimal depth of 10m, no potential, only  $M_2$  tidal forcing)

The scheme is tested on a very coarse mesh of the North- and Baltic Sea with only 7078 nodes. The cost function computes the misfit to 93 tidal gauges.

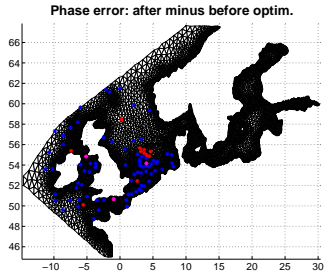
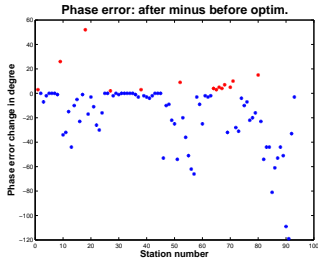
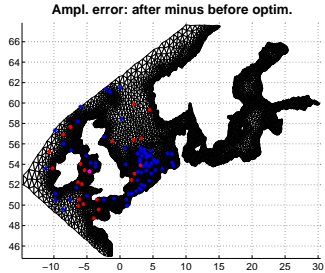
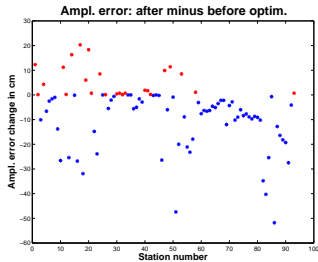




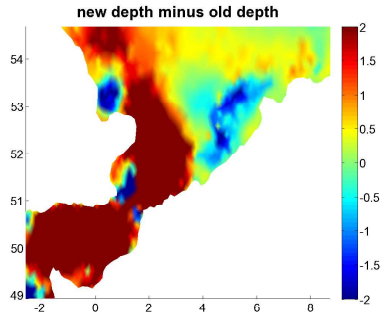
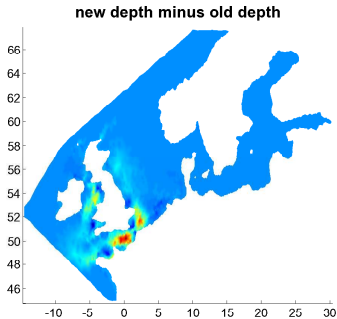
## Initial gradient of the cost function



## Reduction of error (optimized bottom topography and friction)



# Optimized depth with respect to tide gauges



# Conclusions

- ▶ Model is more sensitive to changes in open boundary values than to bottom friction and depth.
- ▶ Error reduction in more than two thirds of the stations.
- ▶ Optimized depth is consistent with our expectation.

# Outlook

- ▶ Compare different AD tools to identify the most efficient
- ▶ Include wetting & drying
- ▶ Analyse the model dependencies to increase computational efficiency of the adjoint model
- ▶ Reduce initial error by taking better bathymetry and finer resolving mesh
- ▶ Optimize parameters for  $M_2$  overtide simulation

