

Drift And Deformation From Satellite Images: Latest European Research (Status October 2015)

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Who in Europe? (“et al.”)

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Reference Systems?

Eulerian:

- velocity and deformation on a spatially fixed (geodetic) grid
- easy to compare to model simulations of sea ice dynamics
- deformation via divergence, shear, vorticity

Laplacian:

- following individual ice floes / ice structures
- reconstruction of path lines (corresponds to drift buoy tracks)
- deformation: as above + area changes of Lagrangian cells

Spatial Scales / Status of Operationalizing?

hemispherical => operational (Met. Norge, IFREMER)

- covering entire Arctic Ocean (/Antarctic) sea ice region
- use of coarse-resolution radiometers/scatterometers

hemispherical / regional patches => operational (DTU,DMI)

- covering only parts of the Arctic/Antarctic per time unit
- use of SAR wideswath modes (e. g. Sentinel-1a EW)

regional => operational (FMI)

- covering Baltic Sea
- use of SAR (Sentinel-1A EWS, Radarsat-2 SCW)

regional / local => experimental

- selected test sites (Baltic, Arctic, Antarctic)
- use of SAR images, different modes

Hemispherical drift fields: Sensors & Spatial / Temporal Resolution

*Passive microwave radiometers: AMSR2 (37 & 89GHz H&V),
SSM/IS (91 GHz H&V) (archived: SSMI)*

Scatterometers: ASCAT (archived: QuikSCAT, NSCAT)

<i>OSI-SAF:</i>	62.5 km	2 days
<i>IFREMER:</i>	62.5 km	3, 6, and 30 days
	31.25 km	2, 3, 6 days

Data available from

(Met Norge) http://osisaf.met.no/p/ice/lr_ice_drift.html

(2007 – present, region: Arctic, (Antarctic) except melting period)

(IFREMER) <http://cersat.ifremer.fr>

(1992 – present; September – May, region: Arctic)

Regional drift fields -> operational: sensors & spatial / temporal resolution

SAR (Sentinel-1, Radarsat-2: wide coverage)

DTU/DMI: 10 km - \geq 1 day (availability)

FMI: 800 m - \geq 1 day (availability)

Data available from:

(DTU/DMI) <http://seaice.dk>, <http://marine.copernicus.eu>

(2010-present, includes also ENVISAT ASAR

recent status: use of all S1-scenes, Arctic > 4000 per month

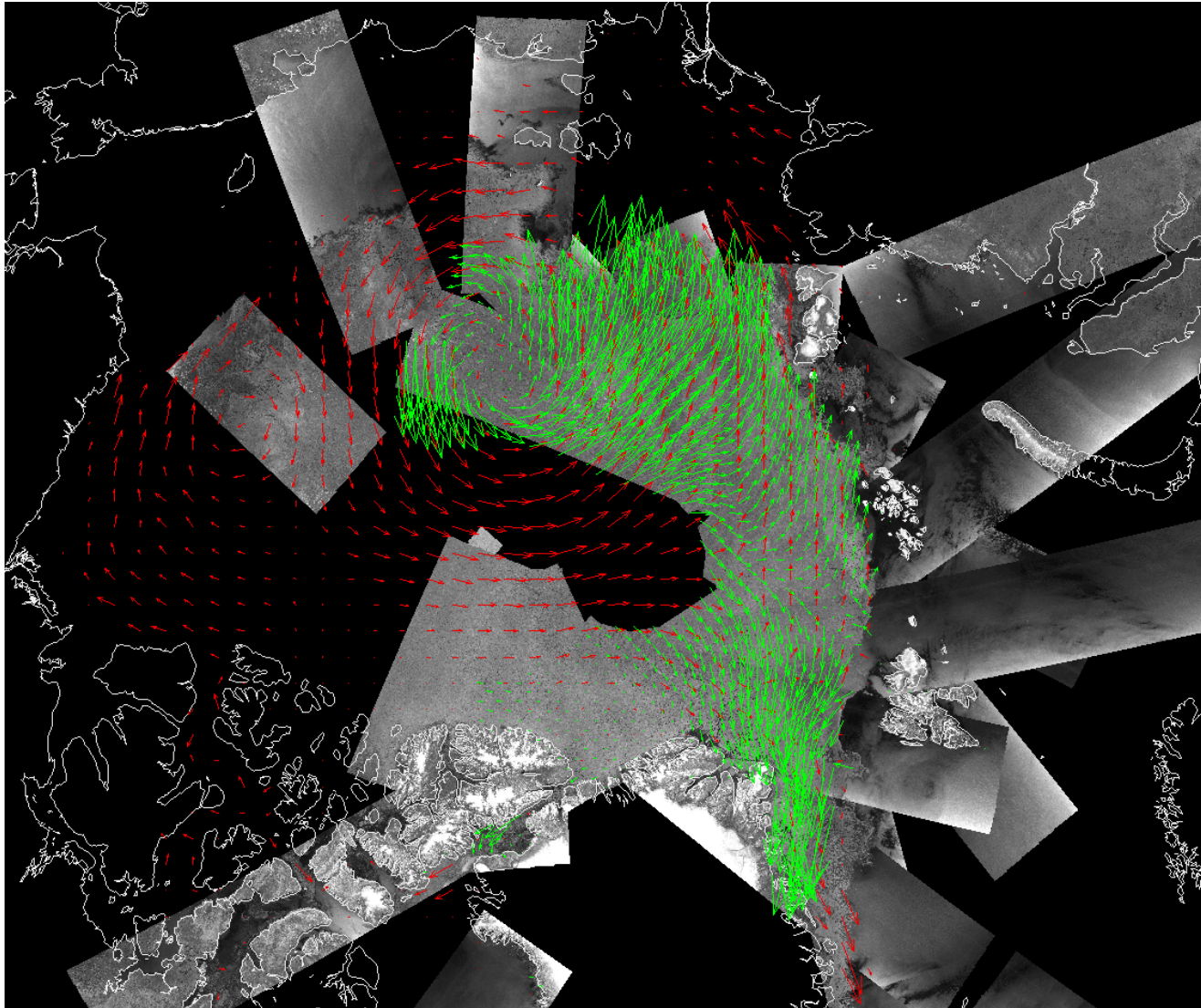
Antarctic > 600 per month)

(FMI) <http://marine.copernicus.eu>

(2011-present, includes also ENVISAT ASAR,

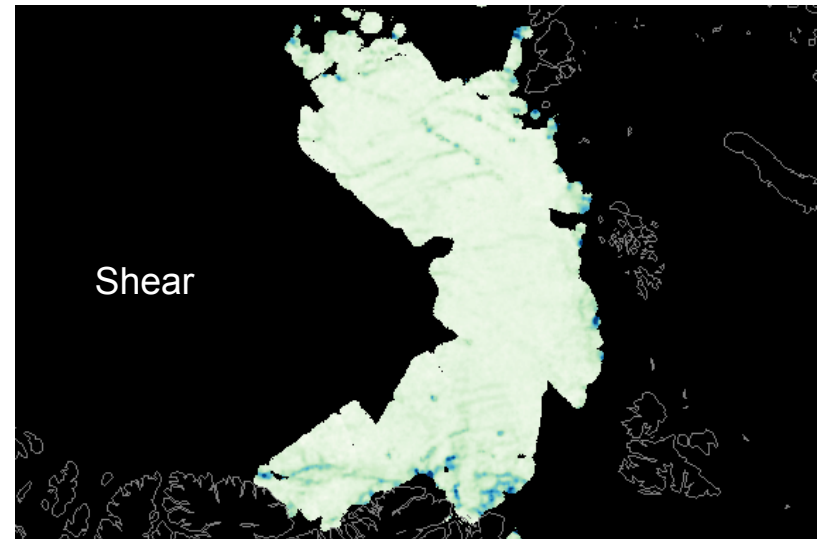
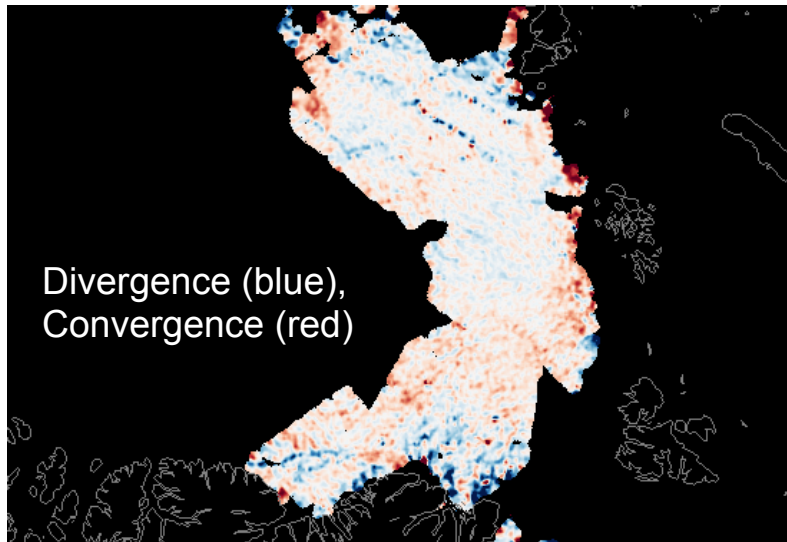
region: Baltic Sea)

Hemispherical / Regional Patches



Arctic ice drift from Sentinel-1A, Oct 10 – 11 2015, www.seaice.dk

Divergence, Shear and Vorticity



- Operational products from DTU, www.seaice.dk, Sentinel-1 October 12-13, 2015
- Produced daily from the 10x10 kilometer Copernicus ice drift data

*Regional / local drift fields -> experimental:
sensors & spatial / temporal resolution*

SAR imagery, recent missions

C-Band: Sentinel-1a, Radarsat-2,

X-Band: TSX/TandemX, Cosmo SkyMED

L-Band: ALOS-2 PALSAR

archived data: ERS-1, -2, Envisat ASAR, Radarsat,
ALOS PaISAR

coverage: 100 – 400 km (few 10s km possible)

spatial resolution: 10-100 m

sp. res. drift fields: about 5-15 times pixel size

Correlations

Maximum Cross-Correlation MCC

- IFREMER, DTU/DMI, FMI, (AWI)
- block (window) correlation in the spatial domain

Continuous MCC

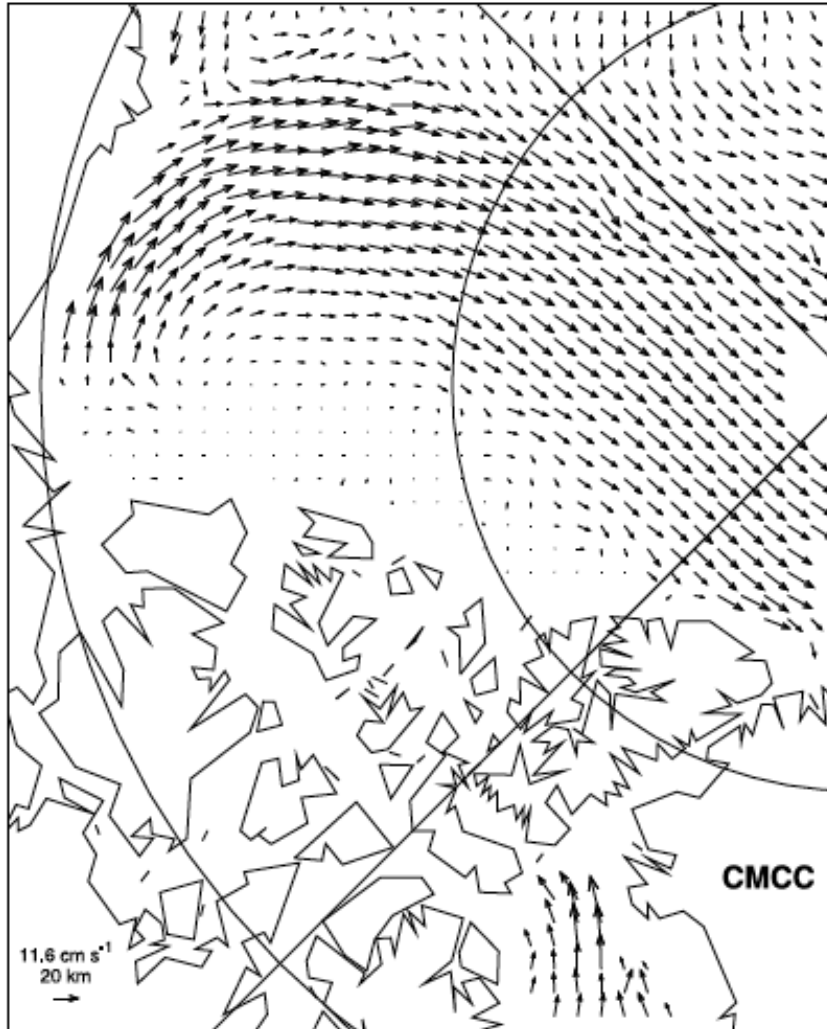
- OSISAF
- based on MCC, increase of lag resolution using pixel interpolation -> reduction of quantization noise

Phase correlation PC

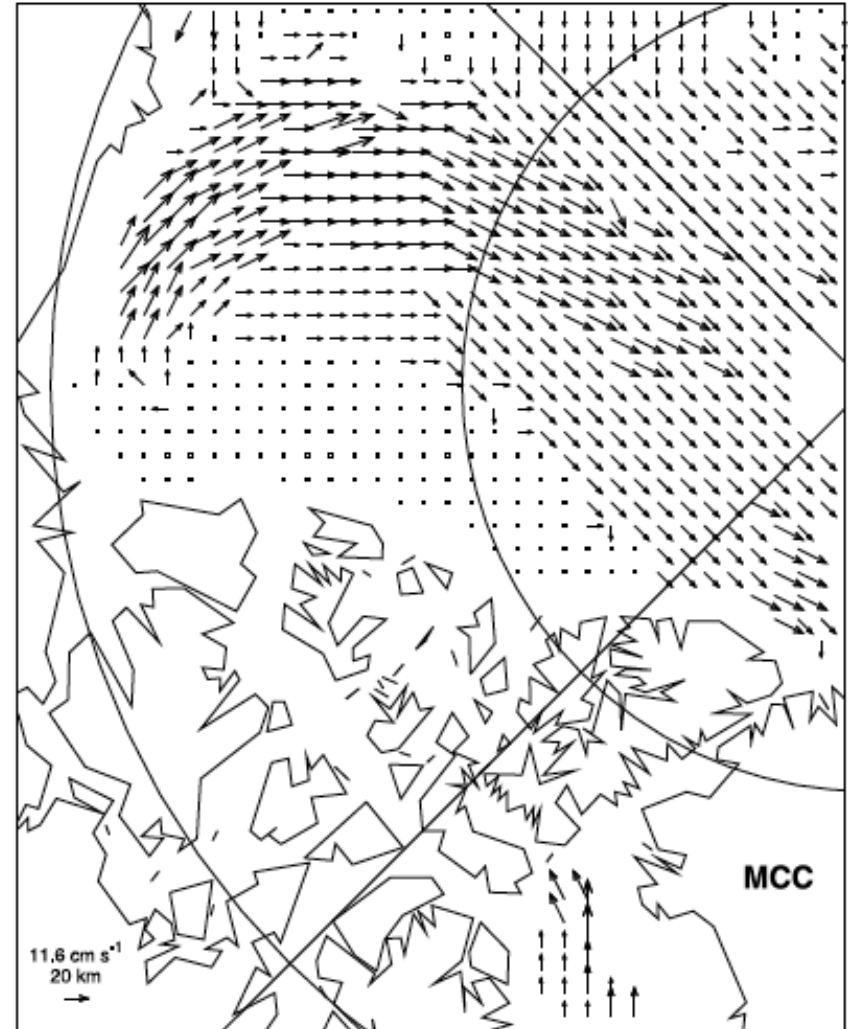
- FMI, Chalmers, (AWI)
- block (window) correlation in the Fourier domain
- (insensitive to changes in intensity, all transform components are weighted equally)

MCC versus CMCC

Sea ice drift from 29 to 31 January 2008



Sea ice drift from 29 to 31 January 2008



Source: Lavergne et al., JGR, 2010

Methods Used?

Pattern matching

- two images needed
- block-wise area correlation (MCC, CMCC, PC)
- preferable for closed pack ice, negligible rotation

Feature tracking

- two images needed
- identification & tracking of stable structures (irregular grid)
- includes rotational motion
- preferable for marginal ice zone

Dopplershift analysis (UiT)

- only one image needed
- use of Sentinel-1 radial surface velocity product
- sub-second line-of-sight ice motion

Problems -> recent work on

- rotation of ice floes / ice floe clusters (correlation)
- discontinuities of the drift field (deformation)
- simultaneous evaluation of drift vector accuracy/reliability
- increase of computational speed
- scaling of drift and deformation

Specification of operational approach using SAR

FMI:

- *PC, 2 levels of spatial resolution with fixed window size*
(second simpler approach: hardware-accelerated MCC)
- *pre-selection of areas to be correlated*
(existence of structures/edges)
- *consideration of multiple drift vector candidates*
(including lower phase correlation peaks and neighbouring vectors for final selection)
- *quality measure*
(magnitude, distance, number of lower phase correlation peaks $> 0.7 \times$ absolute maximum)
- *comparison of different frequency bands (X, C, L)*
(the optimal band depends on sea ice regime)

Specification of experimental approaches

Chalmers:

- *hybrid algorithm: phase correlation & feature tracking*
- *≥ 3 resolution levels*
(simultaneous change of pixel & window size)
- *check for rotation at level of highest spatial resolution*
(dominant rotation within window)
- *image segmentation for ice floe delimitation*
(separation of amalgamated floes; feature tracking on ice floes, but not structures)
- *feature tracking: Least Average Residual Algorithm (LARA)*

Specification of experimental approaches

AWI:

- *phase correlation & subsequent NCC*
(NCC for selection of “candidates” provided by PC)
- *resolution pyramid (pixel size) with cascade (window size)*
(increases robustness of drift vector estimation)
- *quality measures*
 - (> backmatching
 - > confidence factor: effect of speckle
image texture
intensity outliers
correlation)
- *comparison of HH- and HV-polarization (C-band)*
(complementing one another, HV not necessarily better)

Specification of experimental approaches

NERSC:

- *feature tracking*
(ORB = oriented FAST and Rotated BRIEF, open source)
- *FAST: keypoint detector*
(identification of multi-scale features on different levels of spatial resolution with optimum candidate selection)
- *BRIEF: binary strings as feature point descriptor*
(similarity of strings measured by Hamming distance)
- *comparison of HH- and HV-polarization*
(HV significantly better)
- *ongoing: combine pattern matching & feature tracking*
(collaboration with AWI)

Activity 2016/17 : ESA CCI Sea Ice Drift

- During next 2 years, the ESA CCI Sea Ice project will conduct a sea ice drift algorithm intercomparison.
- The target is a climate dataset, but R&D work on algorithms might benefit operational products.
- The project will build a test dataset which collocates image pairs (both SAR, PMR and SCATT) and buoy drift vectors. This dataset will be open and will be used to test existing algorithms.
- Dedicated work on uncertainties is also planned.
- Activity led by T. Lavergne (MET Norway), first results fall 2016.

Source Code Access

- FMI

Open CL cross correlation=> <http://joni.lehtiranta.net/>

- NESRC

ORB algorithm => <http://opencv.org>

SAR processing=> <https://github.com/nansencenter/nansat>

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