

Surface T/S Data RV Polarstern PS96 (ANT-XXXI/2) Data Processing Report

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1 Introduction

This report describes the processing of raw data acquired by the thermosalinographs on board RV Polarstern during expedition PS96 to receive cleaned up and drift corrected salinity data.

2 Workflow

The different steps of processing are visualized in Figure 1. During the cruise, water samples are taken every two days directly from the water inlet of the two thermosalinographs (keel & bow) and measured after temperature equalization with an OPTIMARE Precision Salinometer (OPS) onboard. After the cruise, the measured salinity and temperature data of both sensors are extracted from the DAVIS SHIP database (<https://dship.awi.de>) as 10-minute-means and send together with the salinometer reference measurements to FIELAX for further processing.

First, the data of every cruise is processed separately to determine the offset between the salinometer and the thermosalinograph measurements during the time of water sampling. These offsets are stored until the sensor is replaced and the sensor drift can be calculated for the whole deployment time. The sensor drift of the salinity data is treated as a linear function of months since installation where offset and slope are derived using a least-squares-optimization procedure.

After applying the drift to the 10-min-means from DSHIP, a speed-filter of 0.5 knots minimum is applied, the data are manually despiked and finally, the positions from the corrected mastertracks are assigned as spot-positions for the corresponding times.

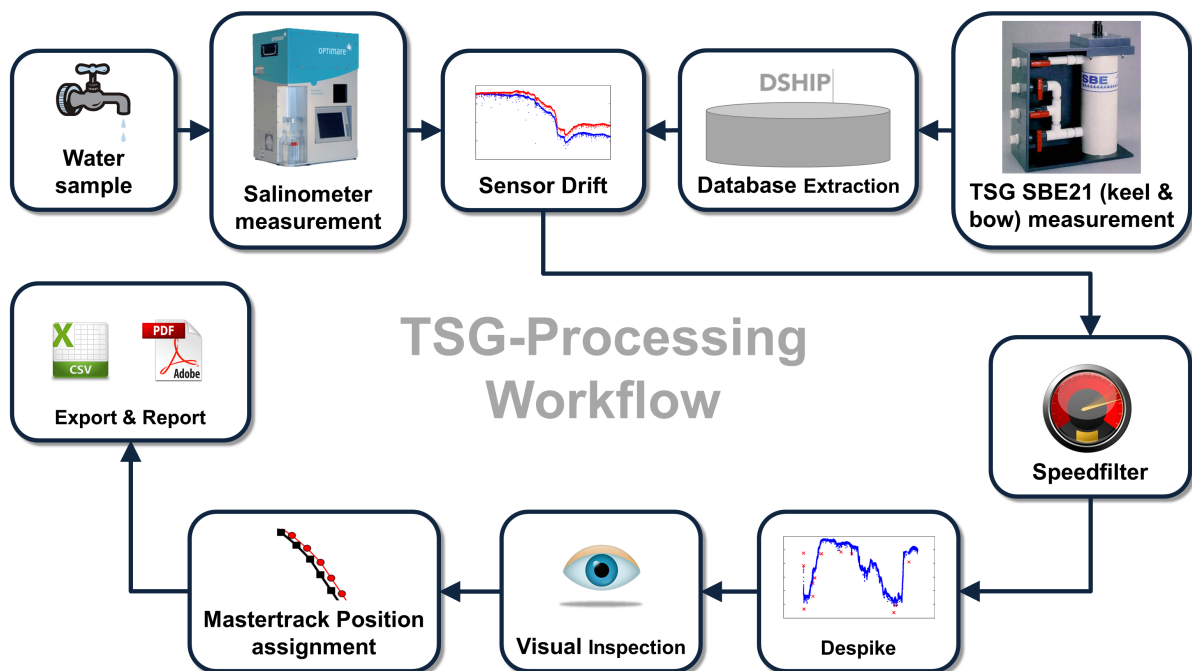


Figure 1: Workflow of Salinity data processing

3 Cruise details

Vessel name RV Polarstern
 Cruise name PS96 (ANT-XXXI/2)
 Cruise start 06.12.2015 Cape Town
 Cruise end 14.02.2016 Punta Arenas
 Cruise duration 61 days

4 Sensors

TS Bow Sensor SBE21 Serial Number: 3189
 TS Keel Sensor SBE21 Serial Number: 3190

5 Processing Report

Database Extraction

Data source	DSHIP database (dship.awi.de)
Exported values	10141
First dataset	2015-12-06T00:00:00 UTC
Last dataset	2016-02-14T10:00:00 UTC

Flagging Result

Deleted Data	TS Bow	TS Keel
No measurement	7937 (78.3%)	203 (2.0%)
Speed < 0.5 knots	62 (0.6%)	2694 (26.6%)
Manually deleted	2142 (21.1%)	4 (0.0%)
Total	10141 (100.0%)	2897 (28.6%)

Comments

Due to a large offset between the Keel and the Bow sensor, the salinity and temperature data of the TS Bow Sensor are omitted.

Sensor Drift TS Bow

Last calibration	02.07.2014
Current calibration	24.11.2016
Start of deployment	06.12.2015
End of deployment	23.10.2016
Drift (between calibrations)	-0.0001 PSU/month
Drift (during deployment)	-0.000271517 PSU/month
Calculated slope	-0.000715342
Calculated offset	-0.012201579

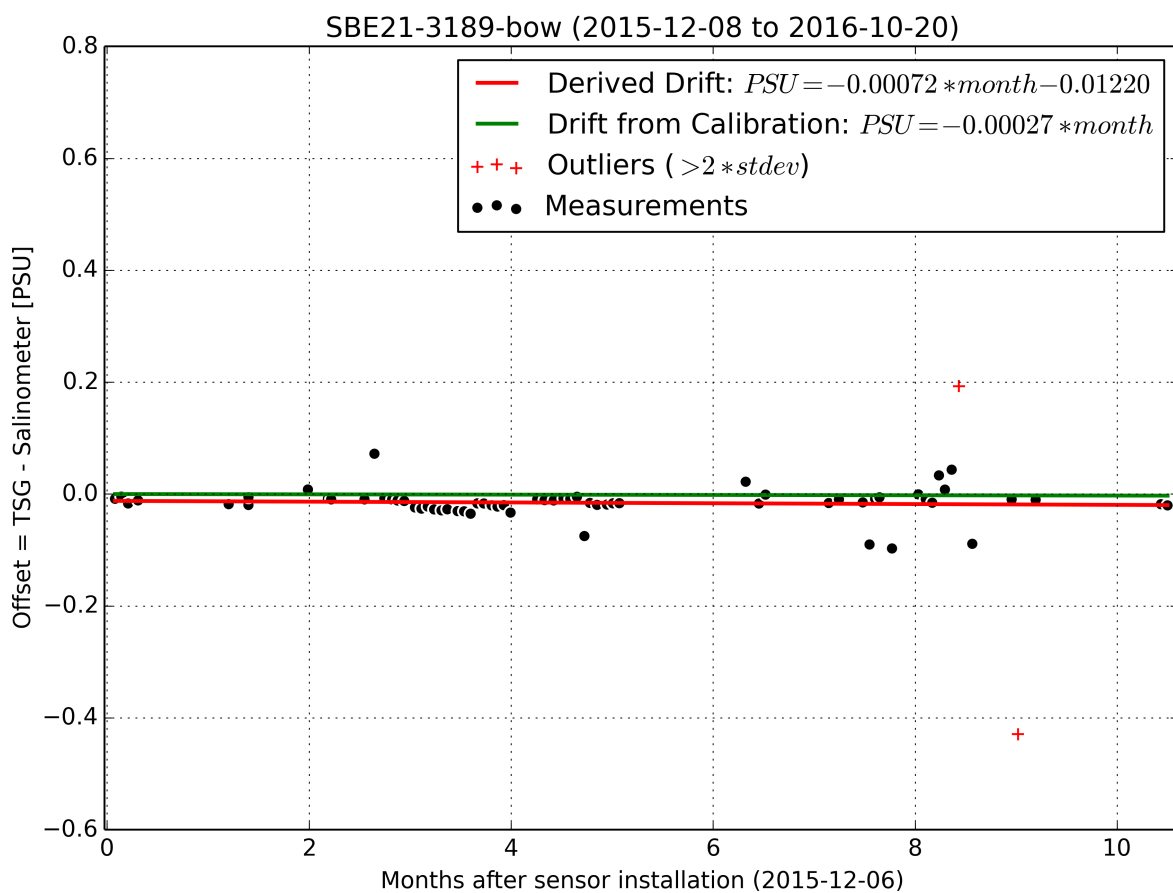


Figure 2: Sensor drift of TS Bow

Sensor Drift TS Keel

Last calibration	06.03.2015
Current calibration	24.11.2016
Start of deployment	06.12.2015
End of deployment	23.10.2016
Drift (between calibrations)	0.0006 PSU/month
Drift (during deployment)	0.001056966 PSU/month
Calculated slope	0.003658363
Calculated offset	-0.061233122

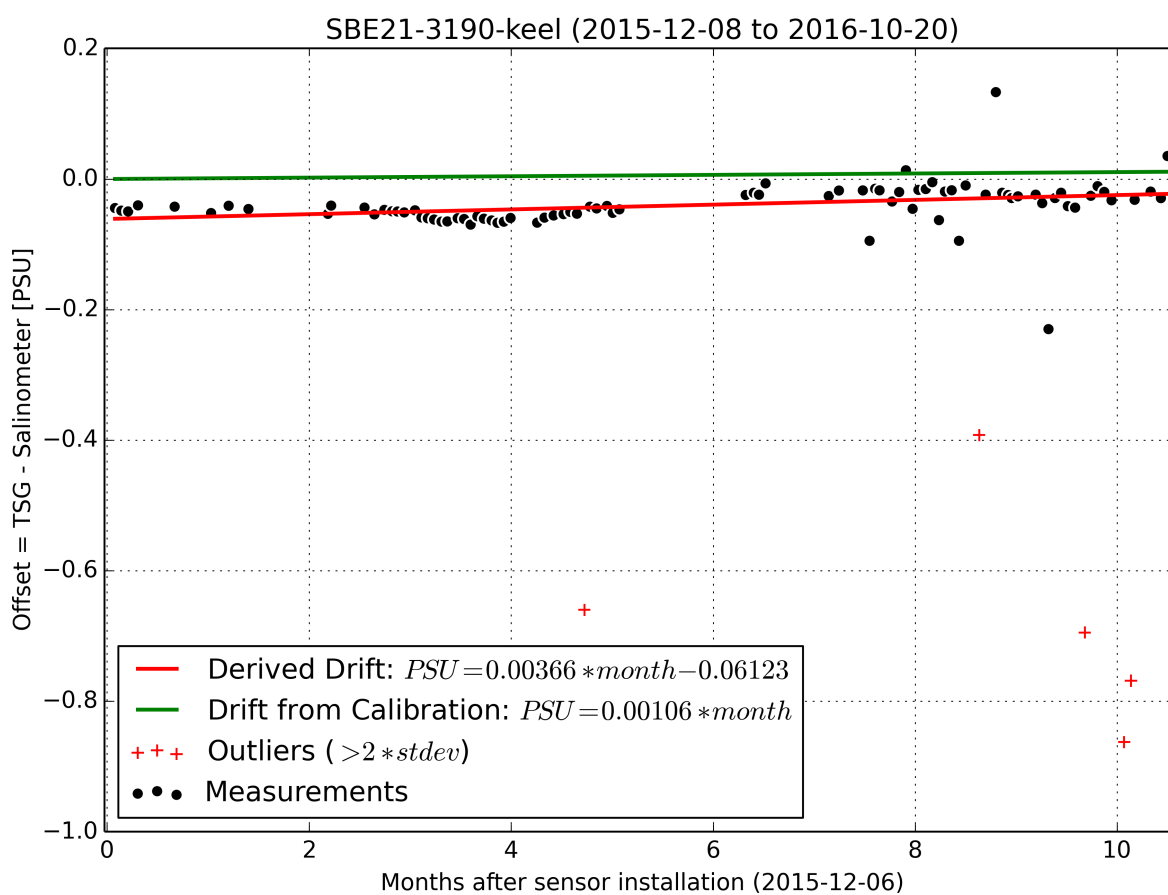


Figure 3: Sensor drift of TS Keel

Result files

Text File (PS96_surf_oce.tab):

The format is a plain text (tab-delimited values) file.

Column separator	Tabulator "\t"
Column 1	Date and time expressed according to ISO 8601
Column 2	Latitude in decimal format, unit degree
Column 3	Longitude in decimal format, unit degree
Column 4	Depth below water surface (Bow = 5m, Keel = 11 m), unit meter
Column 5	Temperature, unit degree
Column 6	Salinity, unit PSU

Processing Report (PS96_TSG.pdf):

This PDF document.

Salinity maps

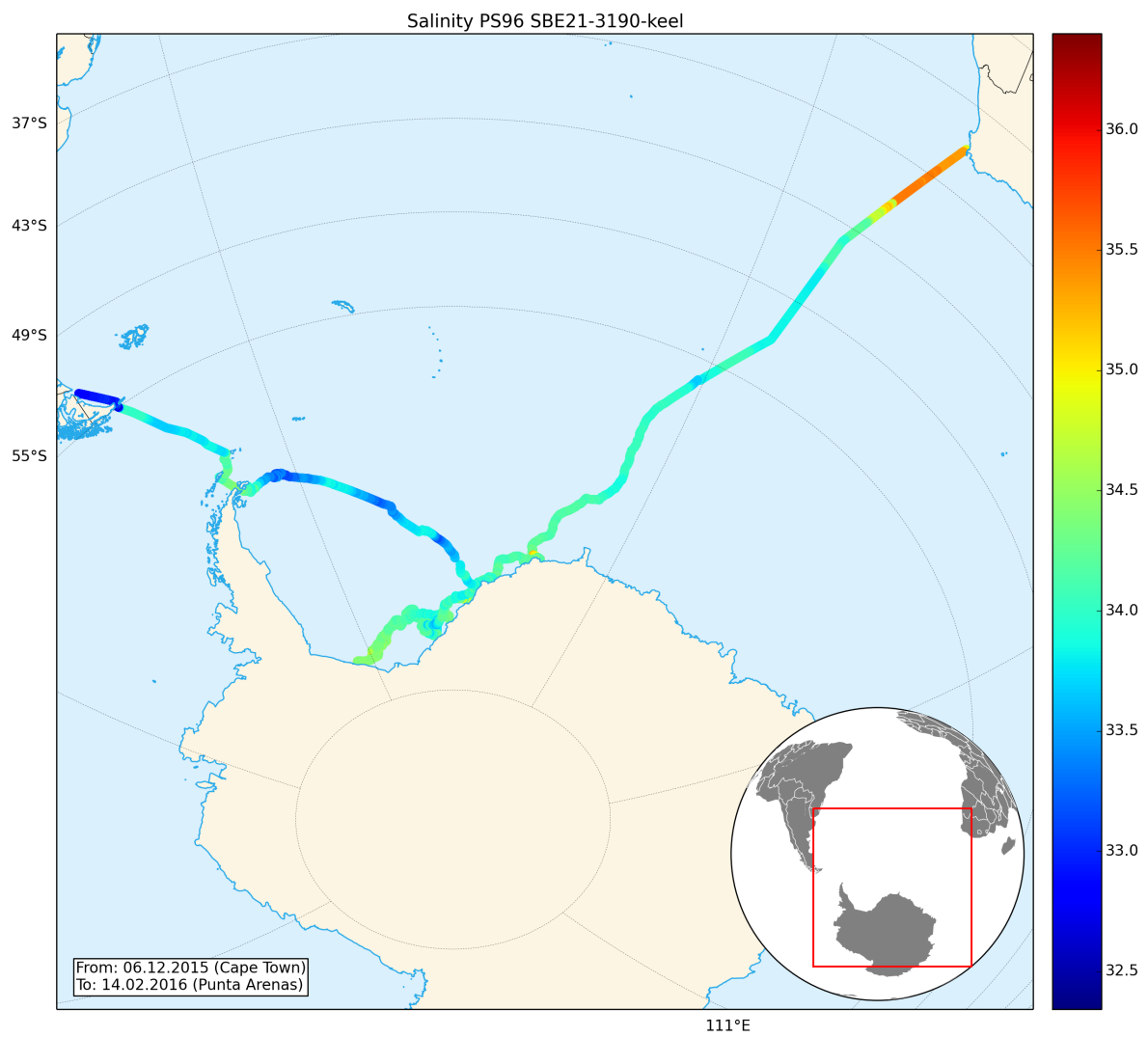


Figure 4: Salinity map of TS Keel