

Underwater Gear Track Data from PS86

Processing Report for USBL Posidonia Data on RV “Polarstern”

Principal Investigator:

Prof. Dr. Antje Boetius

Alfred-Wegener-Institut, Helmholtz-Zentrum für Polar- und Meeresforschung

Am Handelshafen 12, D-27570 Bremerhaven, GERMANY

Phone: +49(471) 4831-2269

Fax: +49(471) 4831-1776

Mail: Antje.Boetius@awi.de

Processing Agency:

FIELAX Gesellschaft für wissenschaftliche Datenverarbeitung mbH

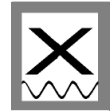
Schleusenstr. 14, D-27568 Bremerhaven, GERMANY

Phone: +49 (0) 471 30015 0

Fax: +49 (0) 471 30015 22

Mail: info@fielax.de

Ref.: FIELAX_Processing-Report_USBL-Navigation_ps86.pdf	Vers.: 1	Datum: 03.09.2014	Status: final
---	----------	-------------------	---------------



1 Introduction

This report describes the processing of raw data acquired by the acoustic underwater positioning system *IXSEA Posidonia* during RV “Polarstern” cruise PS86. Instruments that were tracked during this cruise were: CTD/Water sampler, Television Multicorer (TVMUC) and Ocean Floor Observation System (OFOS).

2 Sensor Information

The *IXSEA Posidonia* is an acoustic underwater positioning system used to determine and track positions of underwater vehicles and instruments. The system is composed of two ultra-short baselines (USBL) consisting of four hydrophones and one main transducer. A *Posidonia* transponder beacon has to be mounted on the instrument to be tracked before the launch. Once the gear is lowered into the water the system’s main transducer transmits an acoustic signal in shape of a 60° wide cone and a frequency of 10.5 kHz to the water. The transponder on the instrument receives this signal and replies with a 9.5 kHz acknowledge signal. This is being received by the four hydrophones of the vessel with small differences in travel time and phase from which a relative angle and distance to the transponder can be calculated. An absolute geographic transponder position and depth is then calculated by applying the ship’s current GPS position, the current motion state (roll, pitch and heading) and a sound velocity profile to compensate the refraction of the signal in the water column. The data is continuously acquired and distributed to the ship’s network to data visualization and mapping programs. The ping rate (reoccurrence time) was set to 10 seconds during this cruise.

3 Processing Workflow

The different steps of processing and validation are visualized in fig. 1. Raw *Posidonia* data (NMEA telegrams, \$PTSAG) is first converted to GIS-readable formats. During visual inspection significant outliers are removed manually. Afterwards the data is filtered by applying a speed filter which eliminates points that have a greater distance to the original track than the tracked instrument could actually have travelled during the given time interval. The data is linearly interpolated to a 1-second interval to be able to reference other instruments’ data or images by time. Output files are written in plain-text (ASCII) format (see next chapter for format description) for each station and navigation overview maps are created.

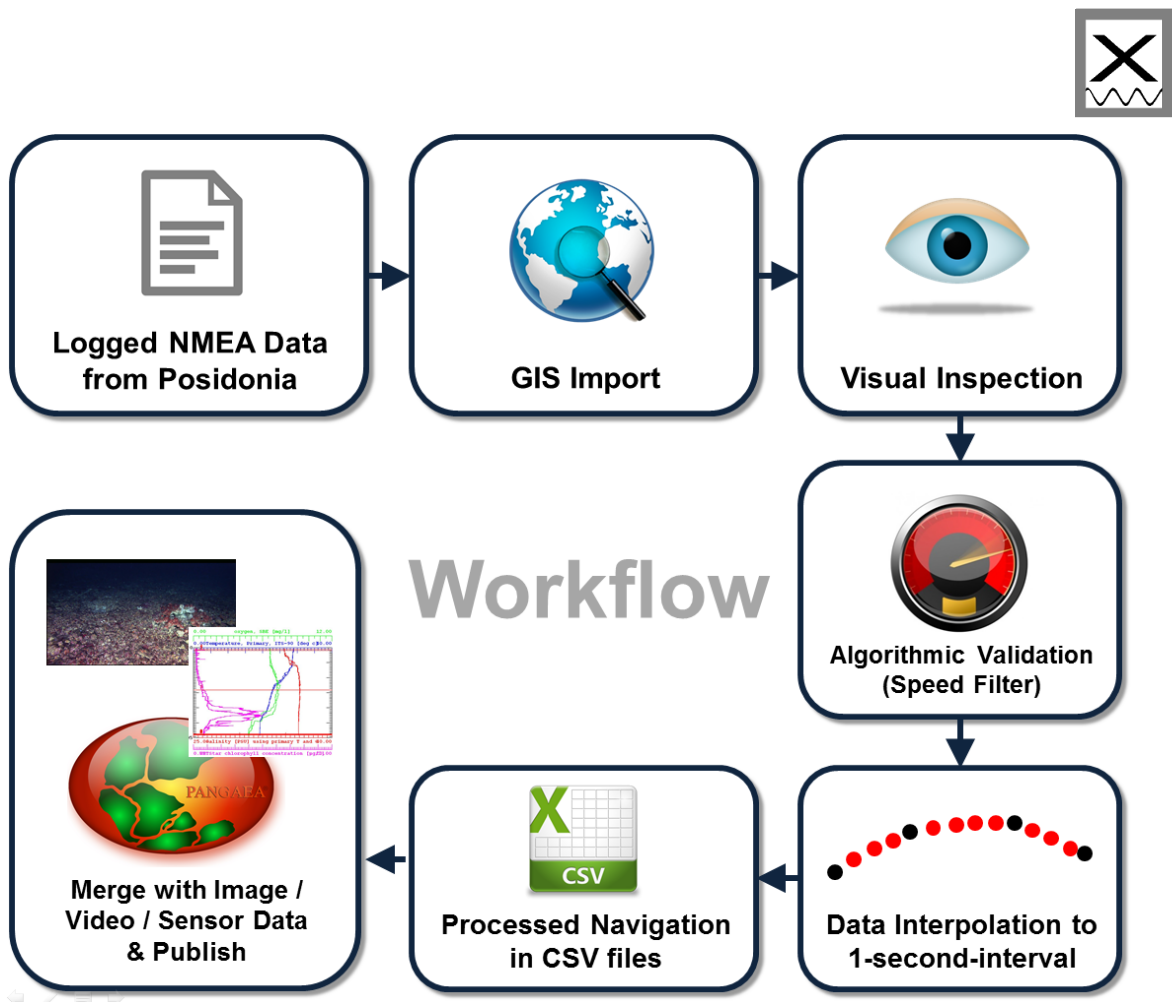


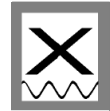
Figure 1: Processing workflow

4 Output Data Format

Result of the processing is a validated and interpolated navigation in 1-second-intervals, held in ASCII table files (tab delimited) as well as an overview map. The file name format is: `<CruiseNo>-<StationNumber>-<StationCast>-<Instrument>-nav_1sec.txt` (Example: `ps86-018-1_CTD_nav_1sec.txt`)

The internal file format is shown here:

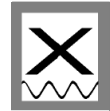
Column No.	Value	Unit, [Range]
1	Date / Time UTC	ISO-8601-conform, YYYY-MM-DDThh:mm:ss
2	Latitude	Decimal Degree, -90°/+90°
3	Logitude	Decimal Degree, -180°/+180°
4	Depth	Meters, positive down



5 Statistics

Overview of *Posidonia*-tracked instrument stations:

Station No.	Gear	Start time	End time	No. of 1s Positions
PS86/0018-1	CTD	2014-07-12T07:44:29	2014-07-12T09:16:06	5499
PS86/0019-1	OFOS	2014-07-12T15:23:32	2014-07-12T18:28:47	11117
PS86/0020-1	TVMUC	2014-07-12T20:12:31	2014-07-12T22:03:04	6635
PS86/0021-1	CTD	2014-07-13T02:17:21	2014-07-13T06:17:12	14393
PS86/0023-1	CTD	2014-07-13T16:48:21	2014-07-13T19:05:45	8246
PS86/0024-1	OFOS	2014-07-13T21:16:14	2014-07-14T01:51:26	16514
PS86/0028-1	TVMUC	2014-07-14T19:18:31	2014-07-14T20:44:52	5183
PS86/0029-1	CTD	2014-07-14T23:00:06	2014-07-15T06:07:22	25638
PS86/0030-1	OFOS	2014-07-15T07:48:25	2014-07-15T12:53:05	18282
PS86/0033-1	CTD	2014-07-15T21:53:41	2014-07-16T00:05:32	7913
PS86/0035-1	OFOS	2014-07-16T13:13:10	2014-07-16T19:48:17	23709
PS86/0036-1	CTD	2014-07-16T21:40:19	2014-07-17T03:21:25	20468
PS86/0039-1	OFOS	2014-07-17T17:35:52	2014-07-17T20:23:15	10045
PS86/0040-1	CTD	2014-07-17T22:40:19	2014-07-18T05:26:37	24380
PS86/0041-1	TVMUC	2014-07-18T07:43:44	2014-07-18T11:40:55	14233
PS86/0043-1	CTD	2014-07-18T21:15:27	2014-07-19T02:29:07	18822
PS86/0046-1	OFOS	2014-07-19T12:33:11	2014-07-19T16:18:38	13529
PS86/0048-1	CTD	2014-07-20T07:16:58	2014-07-20T09:50:23	9207
PS86/0049-1	CTD	2014-07-20T12:01:48	2014-07-20T14:45:58	9852
PS86/0050-1	OFOS	2014-07-20T16:29:51	2014-07-20T20:49:51	15602
PS86/0054-1	OFOS	2014-07-21T19:13:29	2014-07-21T22:16:11	10964
PS86/0055-1	CTD	2014-07-22T04:02:27	2014-07-22T09:10:30	18485
PS86/0056-1	OFOS	2014-07-22T13:26:55	2014-07-22T17:11:42	13489
PS86/0057-1	CTD	2014-07-22T20:05:55	2014-07-22T21:48:56	6183
PS86/0061-1	TVMUC	2014-07-23T18:47:57	2014-07-23T21:23:56	9361
PS86/0065-1	OFOS	2014-07-24T15:11:57	2014-07-24T21:09:34	21459
PS86/0066-1	CTD	2014-07-24T23:26:22	2014-07-25T03:38:16	15116
PS86/0068-1	OFOS	2014-07-25T11:21:32	2014-07-25T17:56:23	23693
PS86/0069-1	CTD	2014-07-25T21:46:56	2014-07-26T03:59:37	22363
PS86/0076-1	TVMUC	2014-07-27T17:56:03	2014-07-27T19:05:11	4150



PS86/0077-1	OFOS	2014-07-27T22:46:29	2014-07-28T01:25:39	9552
PS86/0082-1	OFOS	2014-07-28T21:39:40	2014-07-29T01:08:11	12513
PS86/0083-1	CTD	2014-07-29T03:28:06	2014-07-29T04:05:37	2253
PS86/0084-1	OFOS	2014-07-29T10:54:12	2014-07-29T14:34:17	13207
PS86/0085-1	OFOS	2014-07-29T17:35:31	2014-07-29T20:25:03	10174
PS86/0086-1	OFOS	2014-07-29T22:24:42	2014-07-30T01:27:00	10940

6 Station maps

The station maps give an overview of the processed navigation track. In the upper right corner the cruise and station number is shown as well as the instrument type. For each map the best available bathymetry for the map extent has been chosen. The bathymetry grid source is shown in the lower right corner.

